


The Eastern Ontario Crop Conference
(Kemptville, Ontario)

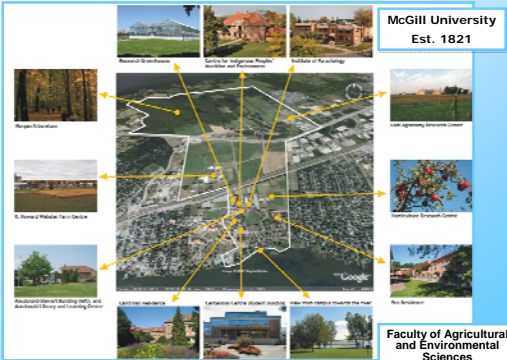
Precision Agriculture The World of Common Sense

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February 10, 2015



Macdonald Campus

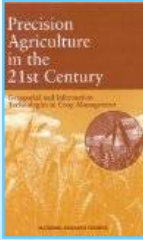


McGill University
Est. 1821

Faculty of Agricultural and Environmental Sciences


Precision Agriculture and Sensor Systems Team

- Development of Proximal Soil and Plant Sensing Systems
- Geospatial Data Processing and Management
- Practical Implementation of Precision Agriculture

“Precision agriculture is a management strategy that uses information technologies to bring data from multiple sources to bear on decisions associated with crop production.”



National Research Council, 1997




WIKIPEDIA
La enciclopedia libre

- La agricultura de precisión es un concepto agronómico de gestión de parcelas agrícolas, basado en la existencia de variabilidad en campo.

October 5, 2012





WIKIPEDIA
The Free Encyclopedia

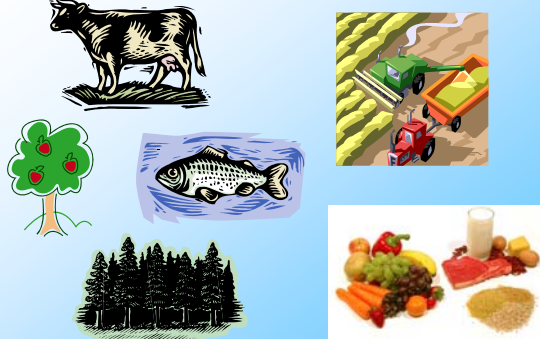
- Precision farming or precision agriculture is a farming management concept based on observing and responding to intra-field variations. Today, precision agriculture is about whole farm management with the goal of optimizing returns on inputs while preserving resources.

October 5, 2012

Goal



Object



System Approach



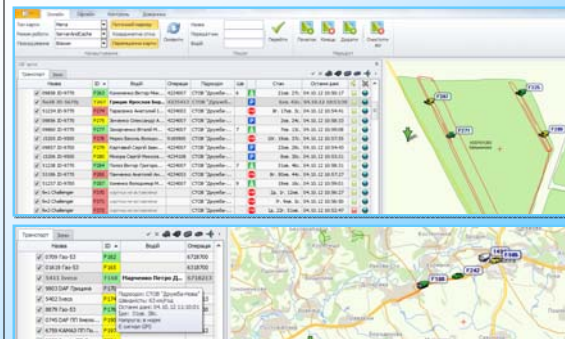
System Approach Implementation

- Conservation tillage
- Machinery use logistics and tracking
- RTK-level auto-guidance
- Automatic section control
- Yield mapping
- Soil electrical conductivity mapping
- Remote sensing (aerial/satellite)
- Soil sampling and analysis
- Band fertilizer placement
- Variable rate nitrogen management
- Variable rate P and K management
- Variable rate seeding

Machinery Tracking



Real-Time Equipment Monitoring



ID	Brand	Model	Serial	Year	Color	Status
01-0001-01-01	John Deere	S780	123456789	2010	Yellow	Working
01-0002-01-02	Case IH	8255	987654321	2011	Red	Idle
01-0003-01-03	Fendt	10T	112233445	2012	Blue	Working
01-0004-01-04	New Holland	CR10.90	556677889	2013	Green	Working
01-0005-01-05	Case IH	8255	1011121314	2014	Red	Working
01-0006-01-06	John Deere	S780	1516171819	2015	Yellow	Working
01-0007-01-07	Case IH	8255	2021222324	2016	Red	Working
01-0008-01-08	Fendt	10T	2526272829	2017	Blue	Working
01-0009-01-09	New Holland	CR10.90	3031323334	2018	Green	Working
01-0010-01-10	Case IH	8255	3536373839	2019	Red	Working

Planting with VRT Seeding and Individual Unit Control

Variable Rate Technology

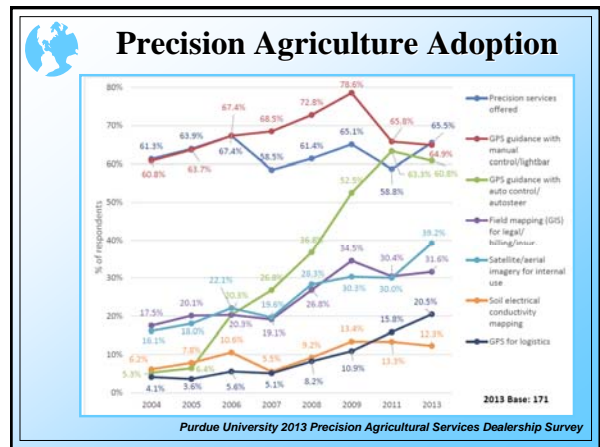
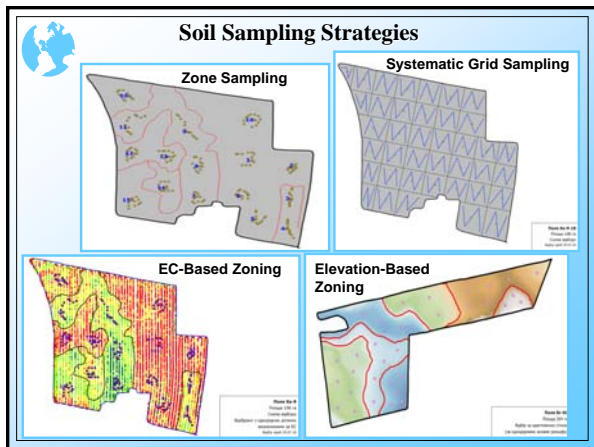
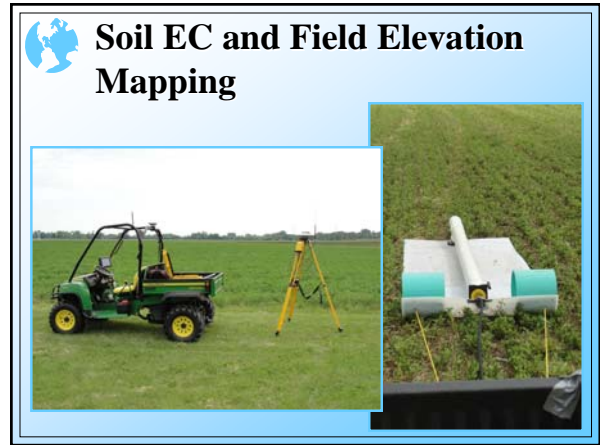
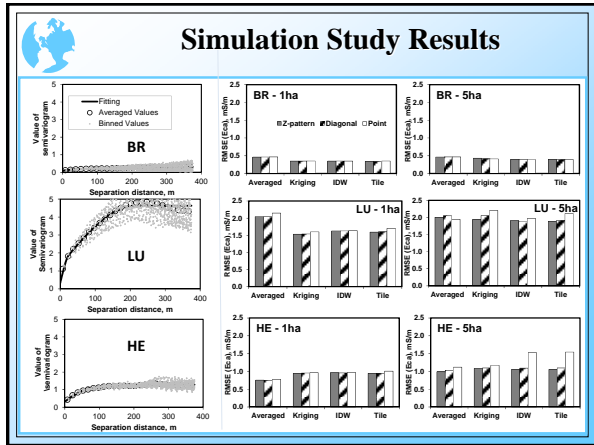
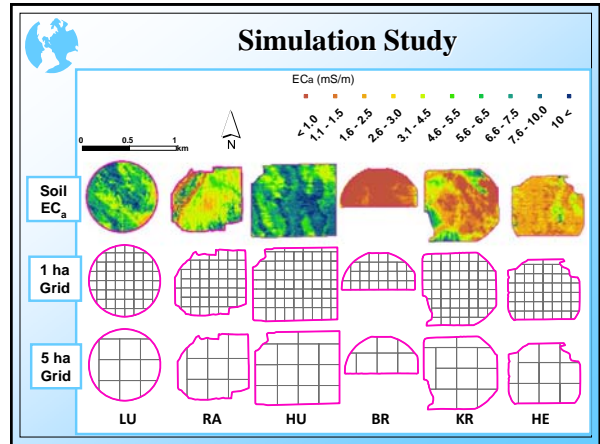
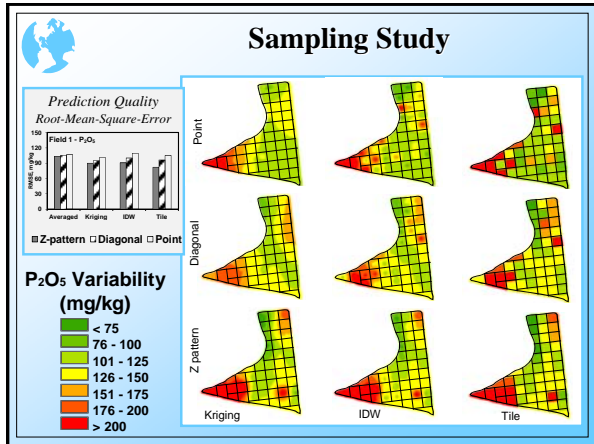
Application Quality Control

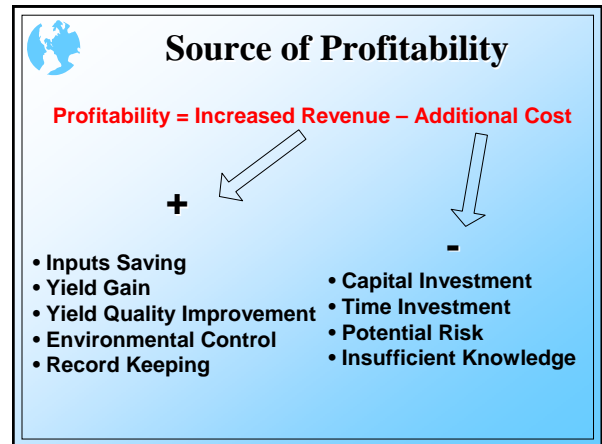
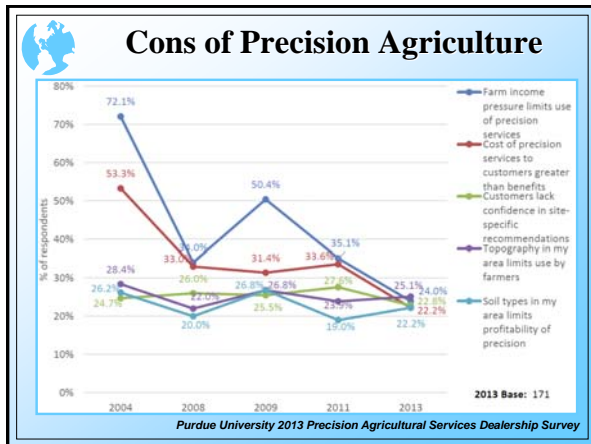
	N	P	K
Status Map			
Prescription Map			
Applied Map			

Georeferenced Soil Sampling

Sampling depth –
0-30 cm and 30-60 cm

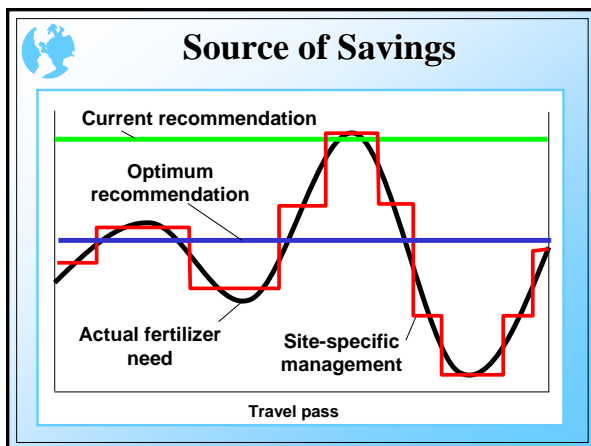
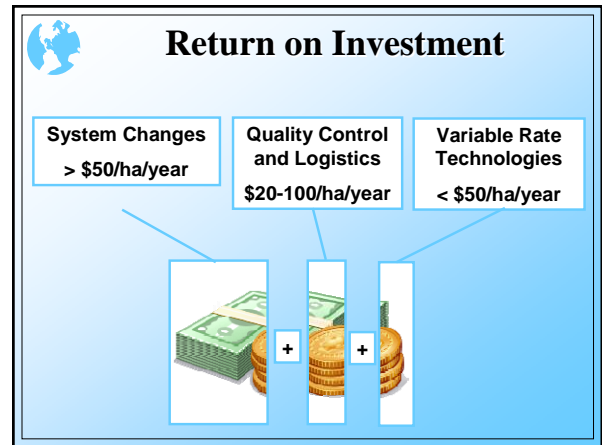
	Center point grid sampling	Diagonal grid cell sampling	Z pattern grid cell sampling
Field 1			
Field 2			





Why Variable Rate Technology?

- It is obvious that skipping, overlapping or placing agricultural outputs outside the cropping area should be avoided
- 4R nutrient stewardship
 - Right fertilizer source
 - Right rate
 - Right time
 - Right place



Tillage

- No-till if possible
- Strip-till to localize main soil treatments
- Spot tillage of compacted areas
- Variable depth tillage in response to the depth of a hard pan



Seeding

- Change rate to account for differences in water availability
- Change depth to optimize emergence
- Change the hybrid in response to local environments



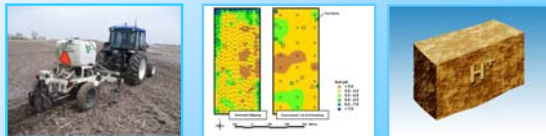
Water

- Field landscaping and drainage
- Control water table
- Optimized irrigation scheduling
- Variable rate irrigation



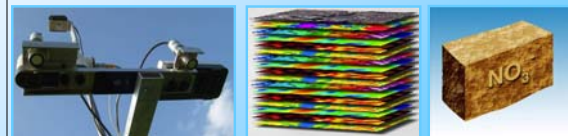
Liming

- More lime is needed for low pH soil
- No lime should be applied to neutral or alkaline soil
- It takes extra lime to raise pH in soils with high buffering capacity



Nitrogen

- Apply when it is needed
- Account for all possible credits (predictive)
 - Potential for mineralization
 - Yield history
 - Residual N
- In season management (reactive)
 - Feed the crop under N stress
 - Do NOT feed the crop under a different type of stress



Potash and Phosphate

- Band placement
- Relevance to past management
- Historic crop removal
- Mapping local needs




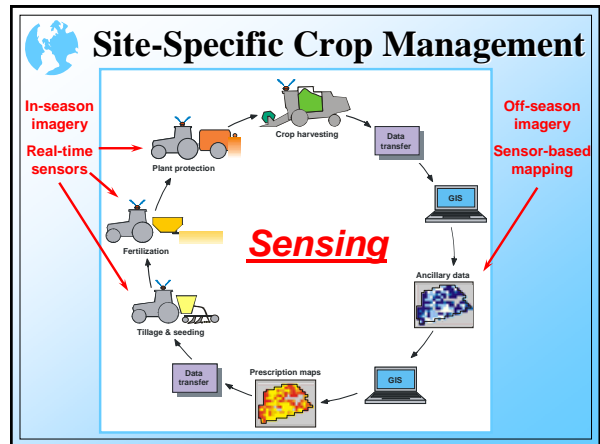
Organic Fertilizers

- Avoid environmentally risky areas
- Nutrient balance in certain cases
- Improved logistics



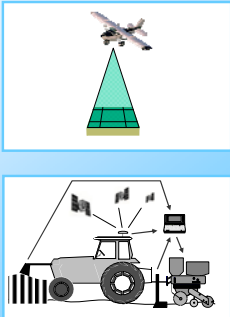
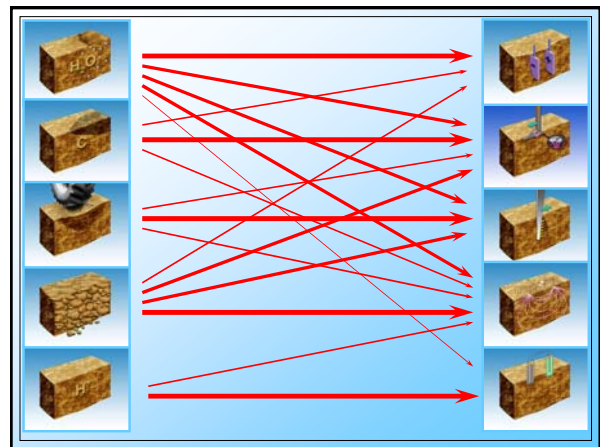
Herbicides

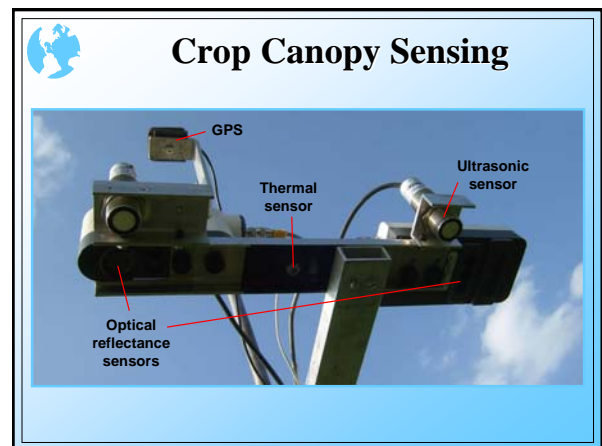
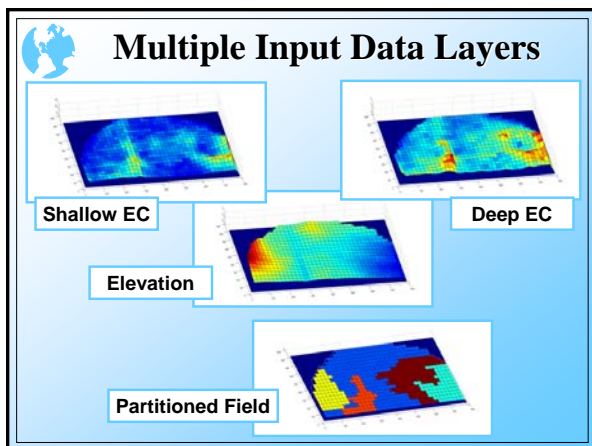
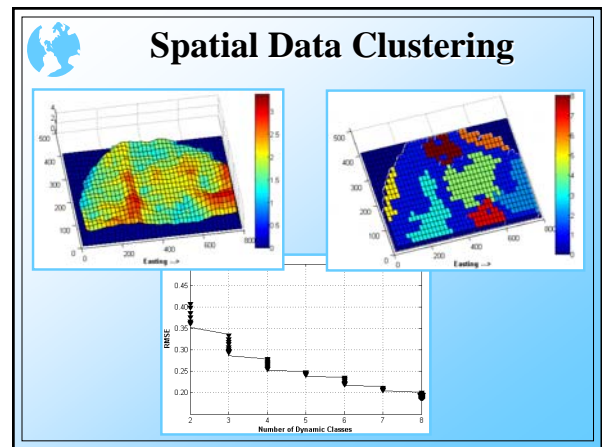
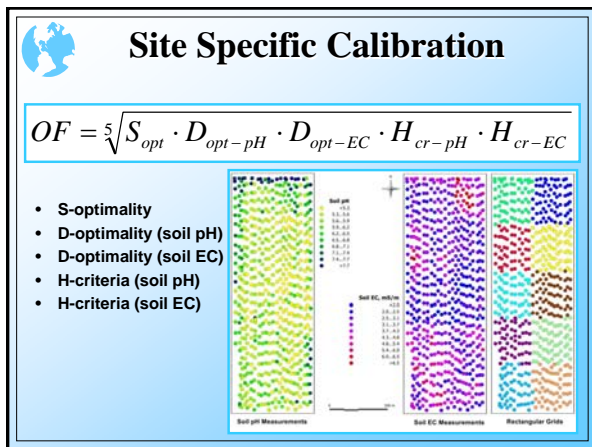
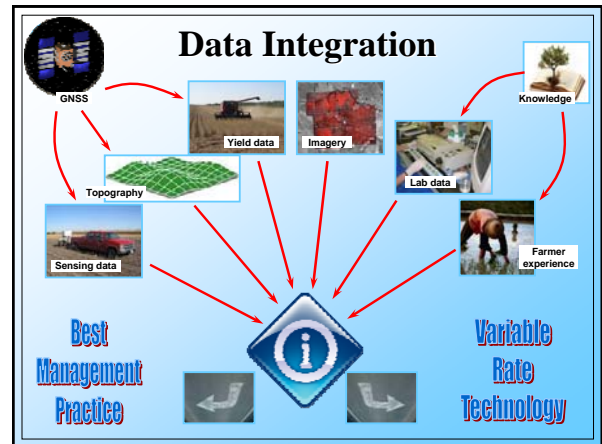
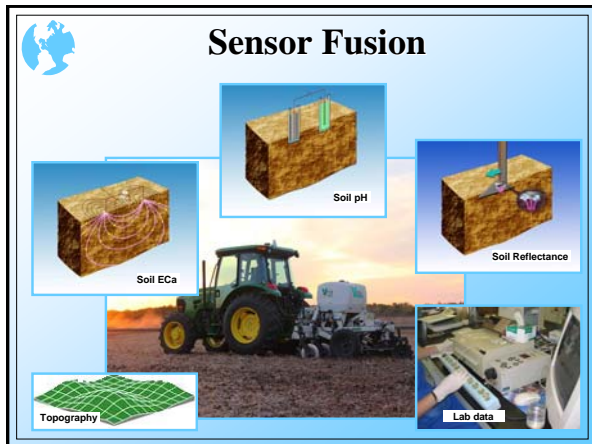
- Change the rate according to the quantity of weeds
- Change the product according to the species
- Change the rate according to soil carbon

Sensing in Precision Agriculture

- Remote
 - Satellite
 - Aircraft
 - UAV
- Proximal
 - On-the-go
 - On-the-spot
 - Profiling



Aerial Imagery

Aerial imagery is presented through a grid of small images, a top-down view of a drone in a grassy field, and a laptop screen displaying a map.

Wireless Sensor Networks

Wireless sensor networks are illustrated by a map with sensor locations, a network of sensors, and a resulting map of real-time water stress impact assessment. The diagram shows a sequence of steps: a map with sensor locations, a network of sensors, and a resulting map of real-time water stress impact assessment.

Map of Real-Time Water Stress Impact Assessment

Soil Profiling Sensors

Soil profiling sensors are shown as a vertical sensor, a graph of soil profile, and a sensor unit. The graph shows a soil profile with depth on the y-axis and soil properties on the x-axis.

On-the-Spot Analyzer

On-the-spot analyzers are shown as a tractor-mounted sensor, a rover-mounted sensor, and detailed views of the sensor components. The detailed views are labeled DETAIL A (SCALE 1:1) and DETAIL B (SCALE 1:1).

MIR Spectroscopy

Diffuse Reflectance Variable Filter Array Mid-Infrared (MIR) spectroscopy - 2780-5096 nm or 5500-10800 nm

MIR spectroscopy setup and graph showing MIR reflectance (%) vs Wavenumber (cm⁻¹) for Clay and Sand samples. The graph shows MIR reflectance (%) on the y-axis (1.4 to 2.2) and Wavenumber (cm⁻¹) on the x-axis (1800 to 800). The legend includes Clay-dry, Clay-less wet, Clay-medium wet, Sand-dry, and Sand-less wet.

In situ Microscopy

In situ microscopy setup showing a laptop displaying a microscopic image, a microscope, and a sample container. The laptop screen shows a microscopic image of a sample.

The Smart Tractor Concept

- Match tractor operation with local conditions according to operator-defined rules or direct operator input
- Use of internal or external sensors to replicate appropriate operation settings

Stage Control

Variable Rate Liquid Cattle Manure Management

Allowed environmentally safe discharge of additional 30% (150 m³) of liquid manure in this 11.1-ha alfalfa field

Proportional Control

Variable Rate Liquid Cattle Manure Management

Allowed environmentally safe discharge of additional 20% (80 m³) of liquid manure in this 12.4-ha corn field

Map-Based Control

Variable Rate Liquid Cattle Manure Management

Input Shape File

Field 26 - Shapefile Test

GPS Speed (km/h)

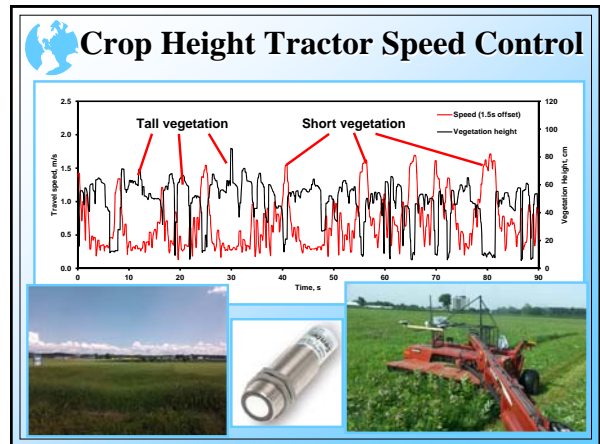
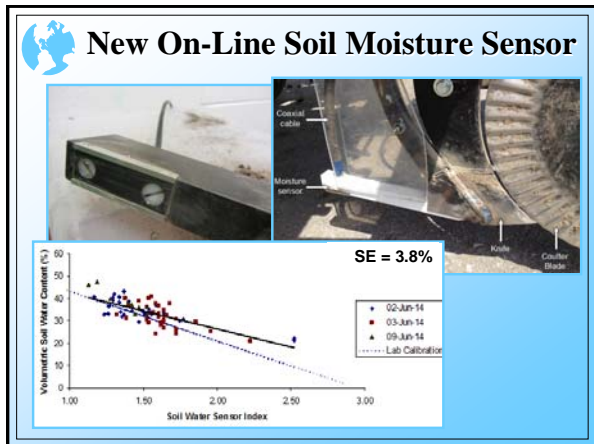
GPS Receiver Speed (km/h)

Prescribed ZoneSpeed

Variable Depth Planting

Planting Depth Control

Soil Water Content Sensing



There is no such a situation where precision agriculture does not work. There are many instances where promoted solutions are not appropriate for solving a given set of problems, or are not executed correctly.

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